

Communications in NLA

September 14, 2020

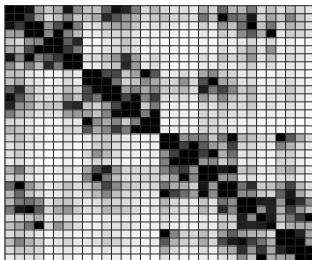
Mixed Precision Low Rank Compression of Data Sparse Matrices

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Slides available at <https://bit.ly/CommNLA>



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Widening range of arithmetics

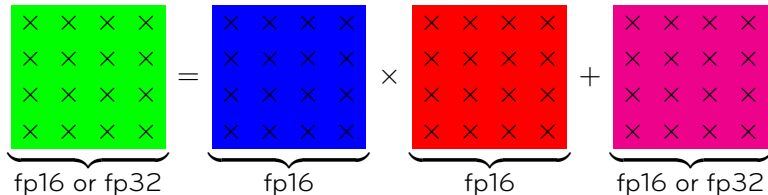
	Bits			
	Signif. (t)	Exp.	Range	$u = 2^{-t}$
bfloat16	8	8	$10^{\pm 38}$	4×10^{-3}
fp16	11	5	$10^{\pm 5}$	5×10^{-4}
fp32	24	8	$10^{\pm 38}$	6×10^{-8}
fp64	53	11	$10^{\pm 308}$	1×10^{-16}
fp128	113	15	$10^{\pm 4932}$	1×10^{-34}

Half precision increasingly **supported by hardware**:

- Fp16 used by NVIDIA GPUs, AMD Radeon Instinct MI25 GPU, ARM NEON, Fujitsu A64FX ARM
- Bfloat16 used by Google TPU, NVIDIA GPUs, Arm, Intel

Benefits from low precisions

- Reduced storage and communications
- Increased speed, e.g., with GPU Tensor Cores

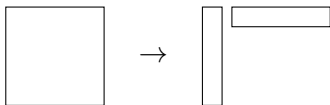


fp32 \rightarrow fp16 speedup evolution:

P100: 2 \times V100: 8 \times A100: 16 \times (announced)

- Correspondingly low accuracy \Rightarrow mixed precision algorithms
- Mixed precision algs. highly successful in NLA: linear systems, matrix factorizations, matrix multiplication, iterative methods, least squares, EVD, SVD, matrix functions, FFT, and many others (see some references at the end of the slides)

$$\begin{array}{ccccc} A & \approx & X & Y^T & \\ n \times n & & n \times r & r \times n & \end{array}$$



- ε -rank of A :

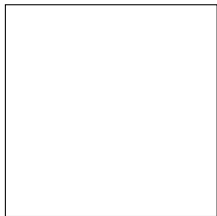
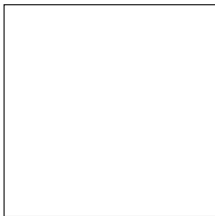
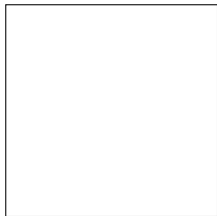
smallest r_ε such that $\exists T$, $\text{rank}(T) = r_\varepsilon$, $\|A - T\| \leq \varepsilon \|A\|$

- Optimal ε -approximation given by truncated SVD (Eckart-Young)

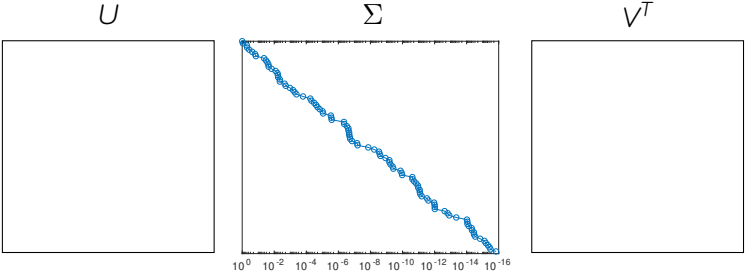
$$A = U \Sigma V^T \Rightarrow T = U_\varepsilon \Sigma_\varepsilon V_\varepsilon^T = \sum_{i=1}^{r_\varepsilon} u_i \sigma_i v_i^T$$

- **What precision should we store T in ?**
- Naive answer: lowest possible precision with unit roundoff safely smaller than ε (e.g., fp64 if $\varepsilon < u_{\text{fp64}} \approx 6 \times 10^{-8}$)

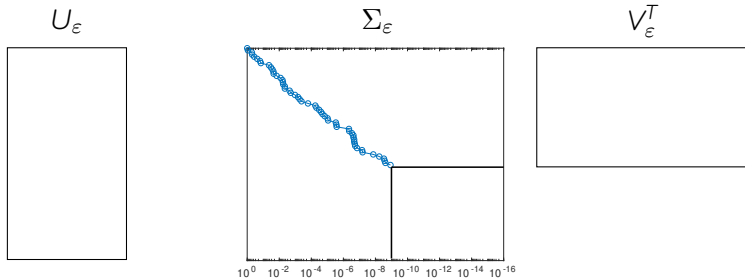
Mixed precision SVD: an example

 U  Σ  V^T 

Mixed precision SVD: an example

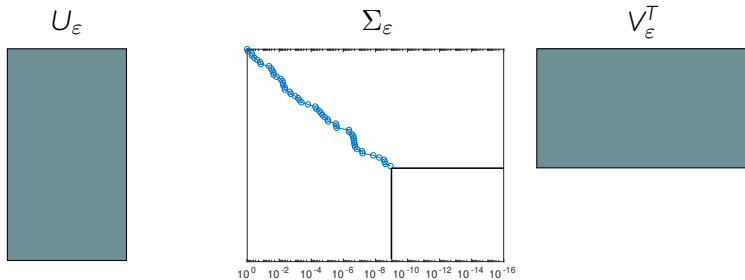


Mixed precision SVD: an example



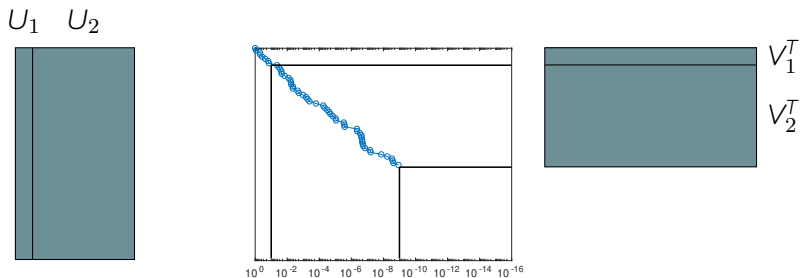
- Assume $\epsilon = 10^{-9} \Rightarrow \|A - U_\epsilon \Sigma_\epsilon V_\epsilon^T\| \leq \epsilon \|A\|$

Mixed precision SVD: an example



- Assume $\epsilon = 10^{-9} \Rightarrow \|A - U_\epsilon \Sigma_\epsilon V_\epsilon^T\| \leq \epsilon \|A\|$
- Naive approach: use **double precision** because $u_{\text{fp32}} > \epsilon$

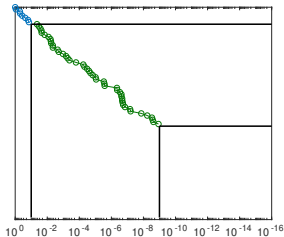
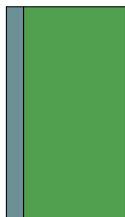
Mixed precision SVD: an example



- Assume $\epsilon = 10^{-9} \Rightarrow \|A - U_\epsilon \Sigma_\epsilon V_\epsilon^T\| \leq \epsilon \|A\|$
- Naive approach: use **double precision** because $u_{\text{fp32}} > \epsilon$
- Let $U_\epsilon = [U_1 \ U_2]$, $\Sigma_\epsilon = \text{diag}(\Sigma_1, \Sigma_2)$, and $V_\epsilon = [V_1 \ V_2]$, such that $\|\Sigma_2\| \leq \epsilon / u_{\text{fp32}} \approx 2 \times 10^{-2}$

Mixed precision SVD: an example

U_1 U_2



- Assume $\epsilon = 10^{-9} \Rightarrow \|A - U_\epsilon \Sigma_\epsilon V_\epsilon^T\| \leq \epsilon \|A\|$
- Naive approach: use **double precision** because $u_{\text{fp32}} > \epsilon$
- Let $U_\epsilon = [U_1 \ U_2]$, $\Sigma_\epsilon = \text{diag}(\Sigma_1, \Sigma_2)$, and $V_\epsilon = [V_1 \ V_2]$, such that $\|\Sigma_2\| \leq \epsilon / u_{\text{fp32}} \approx 2 \times 10^{-2}$
- Our idea: converting U_2 and V_2 to **single precision** only introduces an error of order $u_{\text{fp32}} \|\Sigma_2\| = \epsilon$

- Can use any number of precisions $u_1 \leq \varepsilon < u_2 < \dots < u_p$

$$S_k = \left\{ i \leq r_\varepsilon : \frac{\varepsilon}{u_{k+1}} < \frac{\sigma_i}{\sigma_1} \leq \frac{\varepsilon}{u_k} \right\}, \quad k = 1:p$$

$$U_k \Sigma_k V_k^T = \sum_{i \in S_k} u_i \sigma_i v_i^T \quad \text{and} \quad \hat{T} = \sum_{k=1}^p \hat{U}_k \Sigma_k \hat{V}_k^T$$

where \hat{U}_k and \hat{V}_k are stored in precision u_k .

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where \hat{U}_k and \hat{V}_k are stored in precision u_k . Since for $k \geq 2$

$$\|U_k \Sigma_k V_k^T - \hat{U}_k \Sigma_k \hat{V}_k^T\| \leq (2u_k + u_k^2) \|\Sigma_k\| \leq (2 + u_k) \varepsilon \|A\|$$

we obtain

$$\|A - \hat{T}\| \leq (2p - 1 + \sum_{k=2}^p u_k) \varepsilon \|A\| = O(\varepsilon) \|A\|$$

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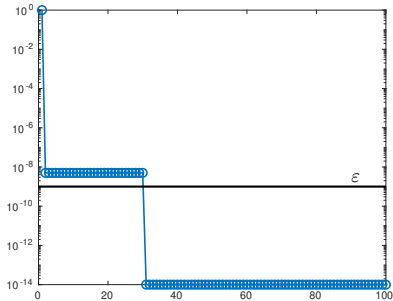
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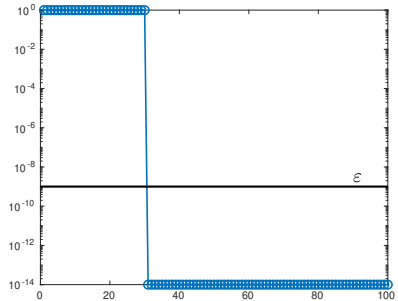
- Applicable to any low rank matrix $XY^T = \sum_{i=1}^{r_\varepsilon} x_i y_i^T$ with **decaying** $\|x_i y_i^T\|$. Example: $AP \approx Q_\varepsilon R_\varepsilon = Q_1 R_1 + \dots + Q_p R_p$

Examples of spectrum

Both matrices have ε -rank 30 (with $\varepsilon = 10^{-9}$) but present very different potential for mixed precision

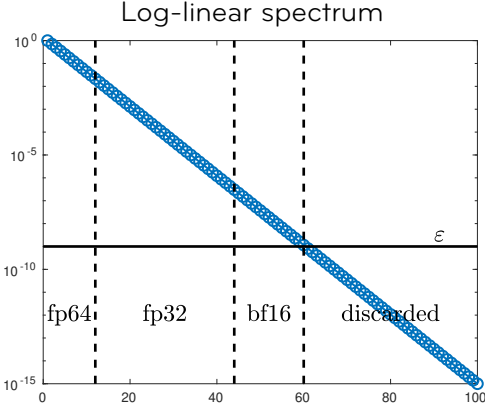


Large gain
(almost all in lower precision)

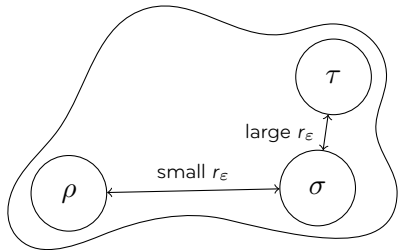
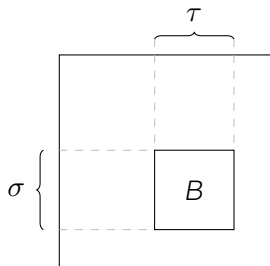


No gain
(all in higher precision)

Examples of spectrum

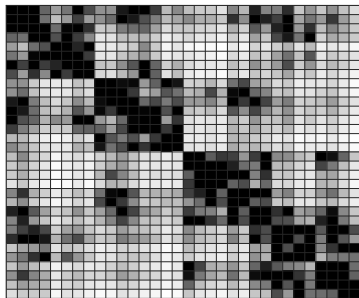


- Data sparse matrices arise in several applications: BEM, PDEs, covariance matrices, ...



- They possess a block low rank structure: a block B represents the **interaction** between two subdomains
 \Rightarrow singular values decay rapidly for far away subdomains
 \Rightarrow **High potential for mixed precision compression**

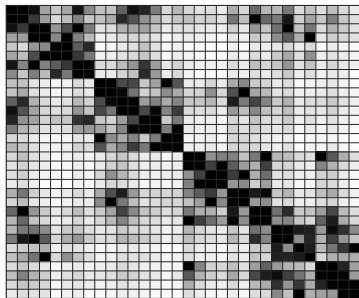
BLR matrices (Amestoy et al.) use a flat 2D block partitioning



Example of a BLR matrix (Schur complement of a 64^3 Poisson problem with block size 128)

- Diagonal blocks are full rank
- Off-diagonal ones are stored in low rank form if their ε -rank is small enough
- $\varepsilon = 10^{-15} \rightarrow 50\%$ entries kept

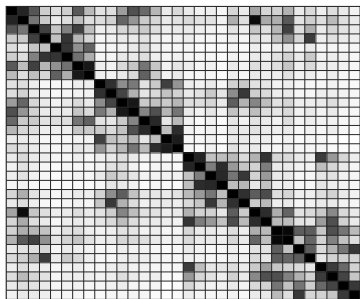
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- $\varepsilon = 10^{-12} \rightarrow 36\%$ entries kept

Example of a BLR matrix (Schur complement of a 64^3 Poisson problem with block size 128)

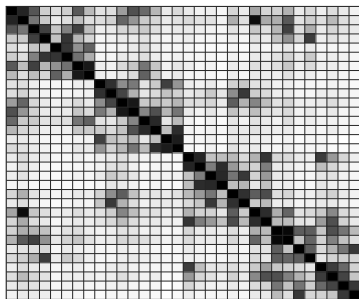
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- $\varepsilon = 10^{-12} \rightarrow 36\%$ entries kept
- $\varepsilon = 10^{-9} \rightarrow 23\%$ entries kept

BLR matrices (Amestoy et al.) use a flat 2D block partitioning



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- $\varepsilon = 10^{-9} \rightarrow 23\%$ entries kept

Example of a BLR matrix (Schur complement of a 64^3 Poisson problem with block size 128)

Hierarchical data sparse matrices (\mathcal{H} , HSS, ...) not covered in this talk, but could also benefit from mixed precision

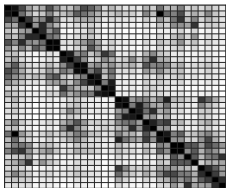
Local vs global uniform precision compression

Should we approximate block $A_{ij} \approx T_{ij}$ such that

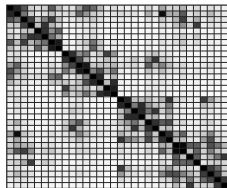
$$\|A_{ij} - T_{ij}\| \leq \varepsilon \|A_{ij}\| \quad (\text{local compression})$$

or $\|A_{ij} - T_{ij}\| \leq \varepsilon \|A\| \quad (\text{global compression}) ?$

- Global compression increases approximation error by a factor at most the number of block-rows/columns
- Generally worth the extra compression coming from blocks of norm less than $\|A\|$ (Higham & M., 2020)



Local compression
(38% entries kept)



Global compression
(23% entries kept)

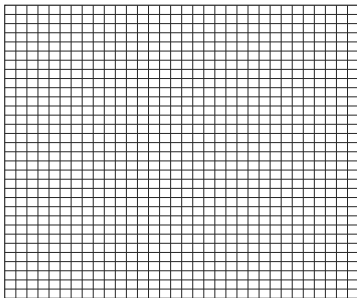
- The set of singular vectors stored in precision u_k for block $A_{ij} = U^{(ij)} \Sigma^{(ij)} V^{(ij)T}$ is

$$S_k^{(ij)} = \left\{ \ell \leq r_\epsilon : \frac{\epsilon}{u_{k+1}} < \frac{\sigma_\ell^{(ij)}}{\sigma_1^{(ij)}} \leq \frac{\epsilon}{u_k} \right\} \quad (\text{local compression})$$

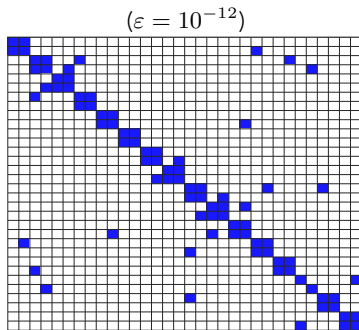
$$S_k^{(ij)} = \left\{ \ell \leq r_\epsilon : \frac{\epsilon}{u_{k+1}} < \frac{\sigma_\ell^{(ij)}}{\|A\|} \leq \frac{\epsilon}{u_k} \right\} \quad (\text{global compression})$$

⇒ With global compression, S_1 may be empty for some blocks
Example: with double and single precisions, blocks such that $\|A_{ij}\| \leq \epsilon/u_{\text{fp32}}\|A\|$ can be stored **entirely in single precision**

$$(\epsilon = 10^{-12})$$

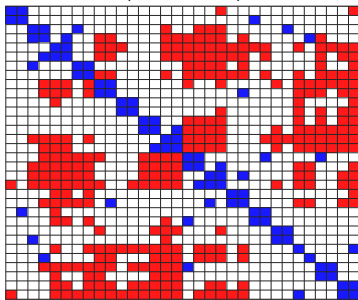


Local vs global mixed precision compression



- Full rank blocks (**near field**) are in **double precision**

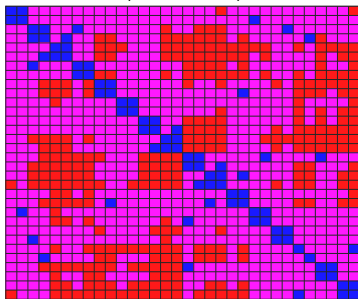
$$(\epsilon = 10^{-12})$$



- Full rank blocks (**near field**) are in **double precision**
- **Far field** blocks are in **single precision**

Local vs global mixed precision compression

$$(\epsilon = 10^{-12})$$



- Full rank blocks (**near field**) are in **double precision**
- **Far field** blocks are in **single precision**
- **Mid field** blocks are in **mixed precision**

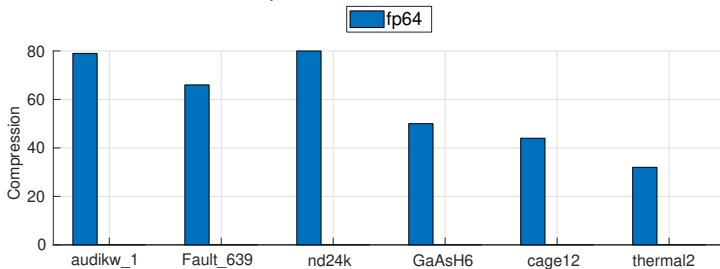
- Dense matrices obtained from the root separator (Schur complement) of sparse matrices

Matrix	Application	n
audikw_1	Structural	3768
Fault_639	Structural	7983
nd24k	2D/3D	7785
GaAsH6	Chemistry	6232
cage12	Graph	7323
thermal2	Thermal	1382

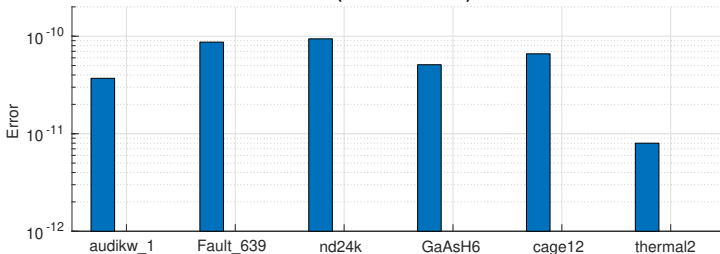
- Block size is set to 128

Numerical results

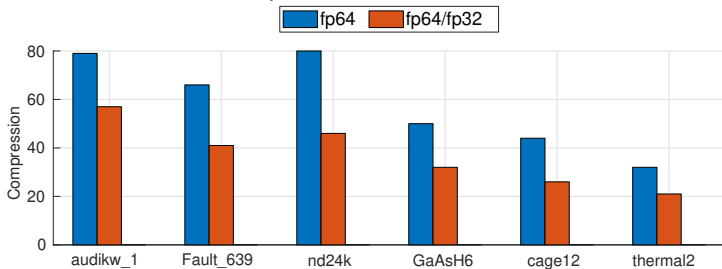
Compression ($\epsilon = 10^{-12}$)



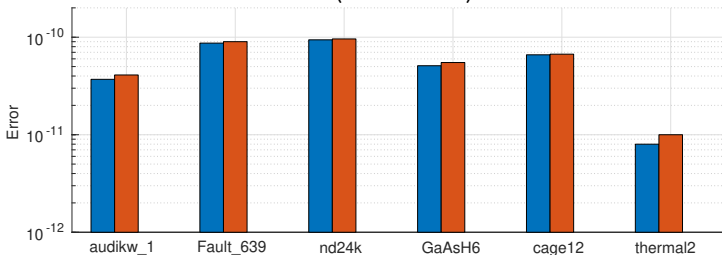
Error ($\epsilon = 10^{-12}$)



Compression ($\epsilon = 10^{-12}$)

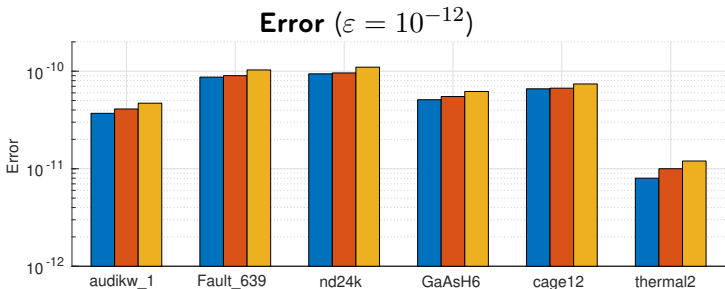
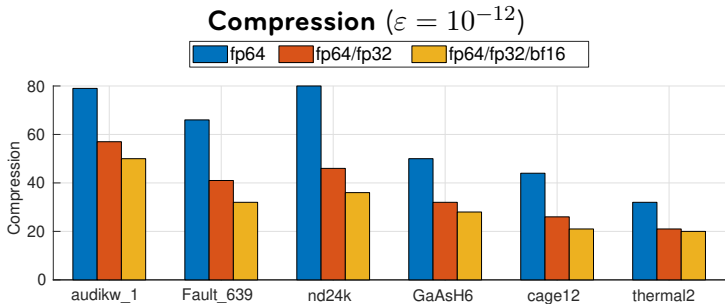


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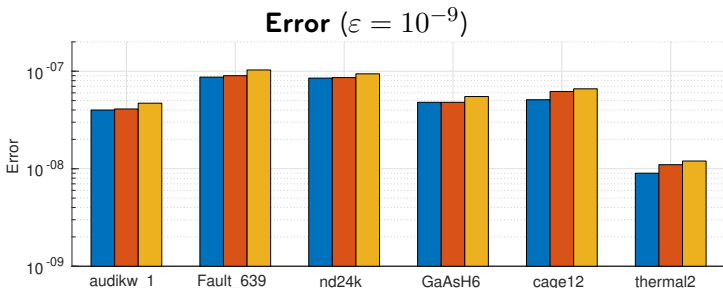
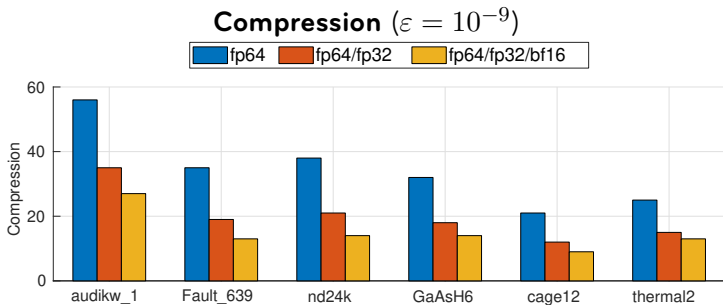


Up to $1.7\times$ storage reduction with almost no error increase

Numerical results

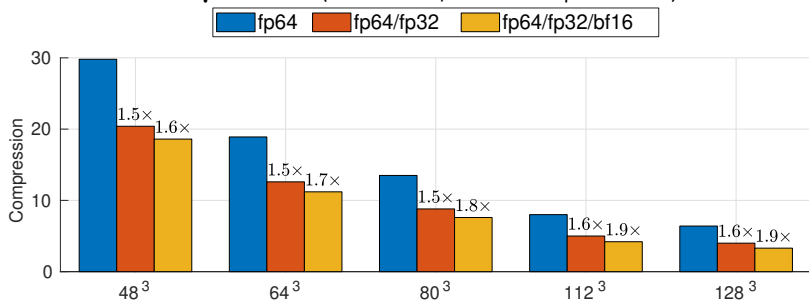


Up to **2.2x** storage reduction with almost no error increase



Up to **2.7x** storage reduction with almost no error increase

Compression ($\epsilon = 10^{-9}$, Poisson problem)



Gain due to mixed precision **increases with problem size:**
 $1.6\times$ (smallest) \rightarrow $1.9\times$ (largest) storage reduction

Mixed precision factorization of data sparse matrices

- Data sparse matrices can be factorized at a much lower cost than dense matrices
- Mixed precision can be used to further reduce this cost
- Example: a mixed precision low rank matrix \hat{T} can be multiplied with a vector v

$$\hat{T}v = \left(\sum_{k=1}^p \hat{U}_k \Sigma_k \hat{V}_k^T \right) v = \sum_{k=1}^p \hat{U}_k \Sigma_k \hat{V}_k^T v$$

by computing $\hat{U}_k \Sigma_k \hat{V}_k^T v$ in precision u_k

- Other NLA operations can also be accelerated

Mixed precision factorization of data sparse matrices

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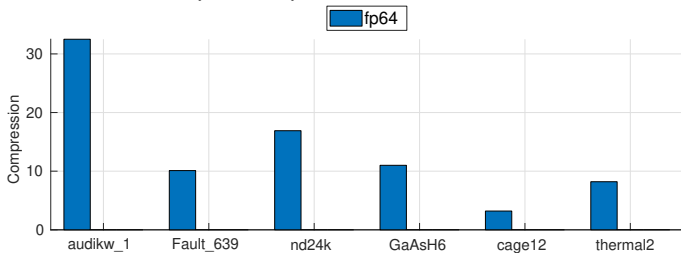
- Other NLA operations can also be accelerated
- Error analysis of BLR factorization in uniform precision u (Higham and M., 2020) shows that

$$A + \Delta A = LU, \quad \|\Delta A\| \leq c_1 \epsilon \|A\| + c_2 u \|L\| \|U\|$$

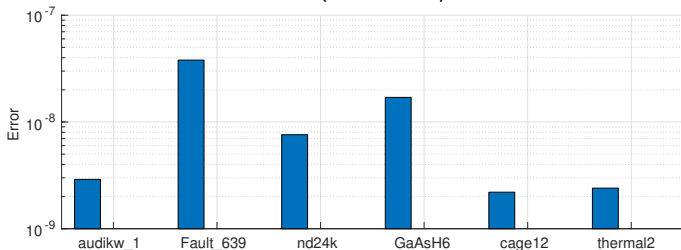
- Analysis can be generalized to mixed precision (ongoing work) with only a modest increase of c_1

Preliminary flops results (no timings yet)

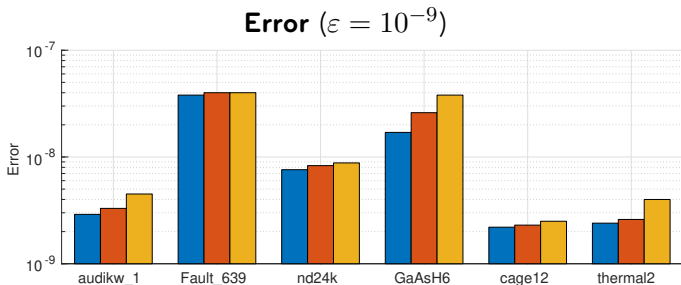
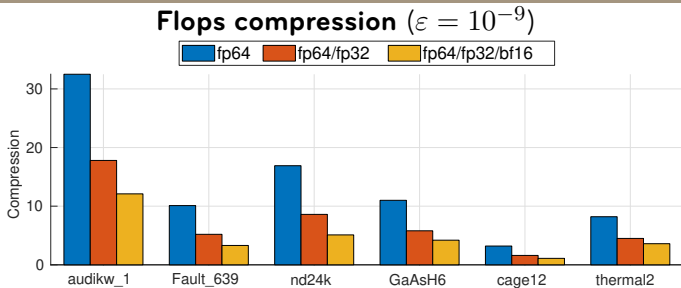
Flops compression ($\epsilon = 10^{-9}$)



Error ($\epsilon = 10^{-9}$)

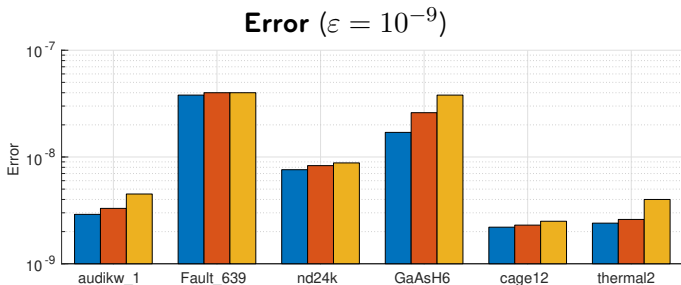
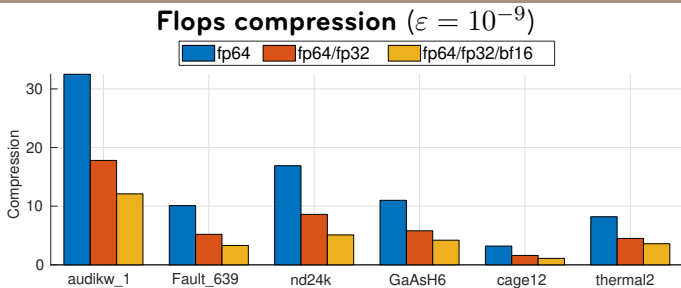


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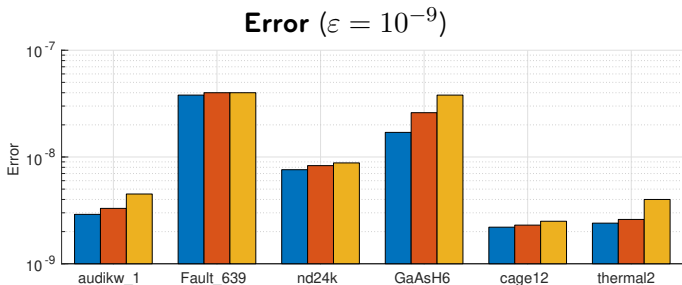
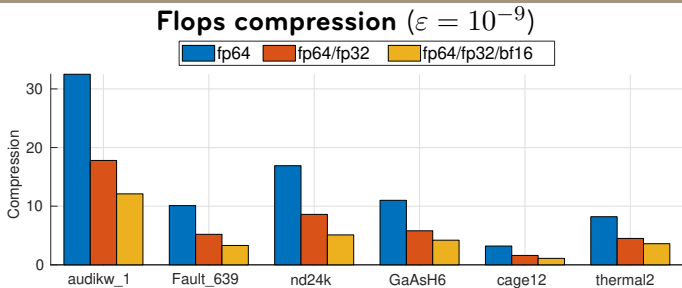
Up to $3.3\times$ flops reduction with almost no error increase

Preliminary flops results (no timings yet)



Up to $3.3 \times$ flops reduction with almost no error increase
→ $3.3 \times$ time reduction??

Preliminary flops results (no timings yet)



Up to $3.3 \times$ flops reduction with almost no error increase
→ $3.3 \times$ time reduction?? $7.0 \times$ with GPU tensor cores

Mixed precision SVD

- Given a matrix A and a target accuracy ε , in what precision should we represent A ?
 - Naive answer: the lowest precision with unit roundoff less than ε
 - Our answer: **it depends on its singular values!**
- ⇒ If rapidly decaying, precisions **lower than ε** can be used
- Also applicable to QR and many other low rank decompositions

Mixed precision compression of data sparse matrices

- Data sparse matrices are an ideal application due to their block low-rank structure
 - Achieved up to **2.7× storage reduction** with fp64/fp32/bfloat16
 - Can also accelerate factorization, up to **3.3× flops reduction**
- ⇒ Much work still needed to transform flops into **time reduction!**

- E. Carson and N. J. Higham. [Accelerating the Solution of Linear Systems by Iterative Refinement in Three Precisions](#). *SIAM J. Sci. Comput.*, 40(2), A817–A847 (2018)
- P. Blanchard, N. J. Higham, and T. Mary. [A Class of Fast and Accurate Summation Algorithms](#). *SIAM J. Sci. Comput.* 42(3), A1541–1557 (2020).
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