Some Results on Structured Pseudospectra

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Outline



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Exploring structures

- 2 Pseudospectra of matrices
 - Unstructured pseudospectra
 - Structured pseudospectra
 - Others structures

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Why structured matrices?

- Structured matrices are used in various fields such as signal processing, etc.
- Using the structure of a matrix, we get some better properties
- Substantial interest in algorithms for structured problems in recent years
- Growing interest in structured perturbation analysis
- In general perturbation and error analysis for structured solvers are performed with *general* perturbations: for a structured solver nothing else but structured perturbations are *possible*

Exploring structures

Pseudospectra of matrices Pseudospectra of matrix polynomials Structured pseudospectra of real matrix polynomials

Our structures

Toeplitz matrices
$$(t_{i-j})_{i,j=0}^{n-1}$$
 $\begin{pmatrix} t_0 & t_{-1} & \cdots & t_{1-n} \\ t_1 & t_0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & t_{-1} \\ t_{n-1} & \cdots & t_1 & t_0 \end{pmatrix}$

 Hankel matrices $(h_{i,j})_{i,j=0}^{n-1}$
 $\begin{pmatrix} h_0 & h_1 & \cdots & h_{n-1} \\ h_1 & h_2 & \ddots & h_n \\ \vdots & \ddots & \ddots & \vdots \\ h_{n-1} & h_n & \cdots & h_{2n-2} \end{pmatrix}$

 Circulant matrices $(v_i)_{i=0}^{n-1}$
 $\begin{pmatrix} v_0 & v_{n-1} & \cdots & v_1 \\ v_1 & v_0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & v_{n-1} \\ v_{n-1} & \cdots & v_1 & v_0 \end{pmatrix}$

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Number of independant parameters

• In the following table, k represents the number of independant parameters for the different structures

Structure	general	Toeplitz	circulant	Hankel	
k	n ²	2n - 1	п	2n - 1	

Notations

Unstructured pseudospectra Structured pseudospectra Others structures

In this talk, we will use the following notation:

structToeplitz, circulant or Hankel $M_n(\mathbf{C})$ set of complex $n \times n$ matrices $M_n^{\text{struct}}(\mathbf{C})$ set of structured complex $n \times n$ matrices $\|\cdot\|$ spectral norm I, I_n identity matrix (with n rows and columns) $\sigma_{\min}(A)$ smallest singular value of A $\Lambda(A)$ spectrum of A

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Definition of pseudospectra

The ε -pseudospectrum of a matrix A, denoted $\Lambda_{\varepsilon}(A)$, is the subset of complex numbers consisting of all eigenvalues of all complex matrices within a distance ε of A

Definition

For a real $\varepsilon > 0$, the ε -pseudospectrum of a matrix $A \in M_n(\mathbb{C})$ is the set

$$\Lambda_{\varepsilon}(A) = \{ z \in \mathbf{C} : z \in \Lambda(X) \text{ where } X \in M_n(\mathbf{C}) \text{ and } \|X - A\| \leq \varepsilon \}.$$

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Distance to singularity

Definition

Given a nonsingular matrix $A \in M_n(\mathbf{C})$, we define the distance to singularity by

$$d(A) = \min\{\|\Delta A\| : A + \Delta A \text{ singular}, \Delta A \in M_n(\mathbf{C})\}$$

Lemma

Let nonsingular $A \in M_n(\mathbf{C})$. Then we have

$$d(A) = \|A^{-1}\|^{-1}.$$

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Characterisation of pseudospectra

Theorem

The following assertions are equivalent

(i)
$$\Lambda_{\varepsilon}(A)$$
 is the ε -pseudospectrum of a matrix A
(ii) $\Lambda_{\varepsilon}(A) = \{z \in \mathbf{C} : ||(zI - A)^{-1}|| \ge \varepsilon^{-1}\}$
(iii) $\Lambda_{\varepsilon}(A) = \{z \in \mathbf{C} : \sigma_{\min}(zI - A)|| \le \varepsilon\}$
(iv) $\Lambda_{\varepsilon}(A) = \{z \in \mathbf{C} : d(zI - A) \le \varepsilon\}$

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Definition of structured pseudospectra

The structured ε -pseudospectrum of a matrix A, denoted $\Lambda_{\varepsilon}^{\mathrm{struct}}(A)$, is the subset of complex numbers consisting of all eigenvalues of all complex structured matrices within a distance ε of A

Definition

For a real $\varepsilon > 0$, the structured ε -pseudospectrum of a matrix $A \in M_n^{\text{struct}}(\mathbf{C})$ is the set

$$\Lambda_{arepsilon}^{ ext{struct}}(A) = \{z \in \mathbf{C} : z \in \Lambda(X) ext{ where } X \in M_n^{ ext{struct}}(\mathbf{C}) \ ext{ and } \|X - A\| \leq arepsilon$$

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Unstructured pseudospectra Structured pseudospectra Others structures

Structured distance to singularity

Definition

Given a nonsingular matrix $A \in M_n^{\text{struct}}(\mathbf{C})$, we define the structured distance to singularity by

 $d^{\text{struct}}(A) = \min\{\|\Delta A\| : A + \Delta A \text{ singular}, \Delta A \in M_n^{\text{struct}}(\mathbf{C})\}.$

Theorem (Rump [8, Thm 12.2])

Let nonsingular $A \in M_n^{\text{struct}}(\mathbf{C})$ with *struct* being Toeplitz , Hankel or circulant. Then we have

$$d^{\text{struct}}(A) = d(A) = ||A^{-1}||^{-1}.$$

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Characterisation of structured pseudospectra

Lemma

Given $\varepsilon > 0$ and $A \in M_n^{\text{struct}}(\mathbf{C})$ with *struct* Toeplitz or circulant, the structured ε -pseudospectrum satisfies

$$\Lambda_{\varepsilon}^{\mathrm{struct}}(A) = \{ z \in \mathbf{C} : d^{\mathrm{struct}}(A - zI) \leq \varepsilon \}.$$

Theorem

Given $\varepsilon > 0$ and $A \in M_n^{\text{struct}}(\mathbf{C})$ with *struct* Toeplitz or circulant, the ε -pseudospectrum and the structured ε -pseudospectrum satisfy

$$\Lambda_{\varepsilon}^{\mathrm{struct}}(A) = \Lambda_{\varepsilon}(A).$$

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What for others linear structures?

We do not have equality for Hermitian and skew-Hermitian structures.

For example for Hermitian structure we always have $\Lambda_{\varepsilon}^{\text{herm}}(A) \subsetneq \mathbf{R}$ whereas one can find an Hermitian matrix such that $\Lambda_{\varepsilon}(A) \nsubseteq \mathbf{R}$.

The polynomial eigenvalue problem

Problem

Find the solutions $(x, \lambda) \in \mathbf{C}^n \times \mathbf{C}$ of

$$P(\lambda)x = 0,$$

where

$$P(\lambda) = \lambda^m A_m + \lambda^{m-1} A_{m-1} + \cdots + A_0,$$

with $A_k \in M_n(\mathbf{C})$, k = 0 : m

If $x \neq 0$ then λ is called an eigenvalue and x the corresponding eigenvector. The set of eigenvalues of P is denoted $\Lambda(P)$. We assume that P has only finite eigenvalues (and pseudoeigenvalues)

Unstructured pseudospectra Structured pseudospectra

Definition of pseudospectra

Let us define

$$\Delta P(\lambda) = \lambda^m \Delta A_m + \lambda^{m-1} \Delta A_{m-1} + \dots + \Delta A_0,$$

where $\Delta A_k \in M_n(\mathbf{C})$.

Definition

For a given $\varepsilon > 0$, the ε -pseudospectrum of P is the set

$$\Lambda_{\varepsilon}(P) = \{\lambda \in \mathbf{C} : (P(\lambda) + \Delta P(\lambda))x = 0 \text{ for some } x \neq 0 \\ \text{with } \|\Delta A_k\| \le \alpha_k \varepsilon, k = 0 : m\}.$$

The nonnegative parameters $\alpha_1, \ldots, \alpha_m$ allow freedom in how perturbations are measured

Unstructured pseudospectra Structured pseudospectra

Characterisation of pseudospectra

Lemma (Tisseur and Higham [9])

$$\Lambda_{\varepsilon}(P) = \{\lambda \in \mathbf{C} : d(P(\lambda)) \leq \varepsilon p(|\lambda|)\},\$$

where $p(x) = \sum_{k=0}^{m} \alpha_k x^k$.

Unstructured pseudospectra Structured pseudospectra

Definition of structured pseudospectra

We suppose that ΔA_k have a structure belonging to struct. We also suppose that all the matrices A_k and ΔA_k , k = 0 : n, belong to $M_n^{\text{struct}}(\mathbf{C})$ for a given structure struct. Let

$$P(\lambda) = \lambda^m A_m + \lambda^{m-1} A_{m-1} + \cdots + A_0,$$

with $A_k \in M_n^{\text{struct}}(\mathbf{C})$, k = 0 : m and

$$\Delta P(\lambda) = \lambda^m \Delta A_m + \lambda^{m-1} \Delta A_{m-1} + \dots + \Delta A_0,$$

where $\Delta A_k \in M_n^{\text{struct}}(\mathbf{C})$. $P(\lambda)$ and $\Delta P(\lambda)$ belong to $M_n^{\text{struct}}(\mathbf{C})$.

Definition

We define the structured ε -pseudospectrum of P by

$$\Lambda_{\varepsilon}^{\text{struct}}(P) = \{\lambda \in \mathbf{C} : (P(\lambda) + \Delta P(\lambda))x = 0 \text{ for some } x \neq 0 \\ \text{with } \Delta A_k \in M_n^{\text{struct}}(\mathbf{C}), \|\Delta A_k\| \leq \alpha_k \varepsilon, k = 0 : n\}.$$

Characterisation of structured pseudospectra

Lemma

For $\mathrm{struct} \in \{\mathrm{Toep}, \mathrm{circ}, \mathrm{Hankel}\}$, we have

$$\Lambda^{ ext{struct}}_arepsilon(\mathcal{P}) = \{\lambda \in \mathbf{C}: d^{ ext{struct}}(\mathcal{P}(\lambda)) \leq arepsilon \mathcal{P}(|\lambda|) \},$$

where
$$p(x) = \sum_{k=0}^{n} \alpha_k x^k$$
.

Theorem

Given $\varepsilon > 0$ and $P(\lambda) \in M_n^{\text{struct}}(\mathbf{C})$ a matrix polynomial with $\text{struct} \in \{\text{Toep, circ, Hankel}\}$, the ε -pseudospectrum and the structured ε -pseudospectrum satisfy

$$\Lambda_{\varepsilon}^{\mathrm{struct}}(P) = \Lambda_{\varepsilon}(P).$$

Real structured perturbations

Consider

$$P(\lambda) = \lambda^m A_m + \lambda^{m-1} A_{m-1} + \cdots + A_0,$$

with $A_k \in M_n(\mathbf{R})$, k = 0 : m and

$$\Delta P(\lambda) = \lambda^m \Delta A_m + \lambda^{m-1} \Delta A_{m-1} + \cdots + \Delta A_0,$$

where $\Delta A_k \in M_n(\mathbf{R})$. Suppose that $P(\lambda)$ is subject to structured perturbations:

$$[\Delta A_0,\ldots,\Delta A_m]=D\Theta[E_0,\ldots,E_m],$$

with $D \in M_{n,1}(\mathbb{R})$, $\Theta \in M_{1,t}(\mathbb{R})$ and $E_k \in M_{t,n}(\mathbb{R})$, k = 0 : m. For notational convenience, we introduce

$$E(\lambda) = E[I_n, \lambda I_n, \dots, \lambda^m I_n]^T = \lambda^m E_m + \lambda^{m-1} E_{m-1} + \dots + E_0,$$

and

$$G(\lambda) = E(\lambda)P(\lambda)^{-1}D = G_R(\lambda) + iG_I(\lambda), \quad G_R(\lambda), G_I(\lambda) \in \mathsf{R}^t.$$

Definition and characterisation of pseudospectra

Definition

The structured ε -pseudospectrum is defined by

 $\Lambda_{\varepsilon}(P) = \{\lambda \in \mathbf{C} : (P(\lambda) + D\Theta E(\lambda))x = 0 \text{ for some } x \neq 0, \|\Theta\| \leq \varepsilon\}$

We denote for $x, y \in \mathbf{R}^t$,

$$d(x, \mathbf{R}y) = \inf_{\alpha \in \mathbf{R}} \|x - \alpha y\|,$$

the distance of the point x from the linear subspace $Ry = \{ \alpha y, \alpha \in R \}.$

Theorem

 $\Lambda_{\varepsilon}(P) = \{\lambda \in \mathbf{C} \setminus \Lambda(P) : d(G_{R}(\lambda), \mathbf{R}G_{I}(\lambda)) \geq 1/\varepsilon\} \cup \Lambda(P)$



We have

- The structured pseudospectrum is equal to the pseudospectrum for the two following structures: Toeplitz and circulant
- This result is false for structures Hermitian and skew-Hermitian
- We have generalized these results to pseudospectra of matrix polynomials.
- We have given a formula for structured pseudospectra of real matrix polynomials



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