

Reproducibility of sparse matrix-vector product and sparse solvers

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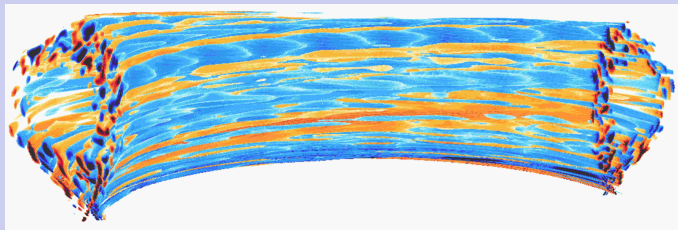
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Zürich, Switzerland

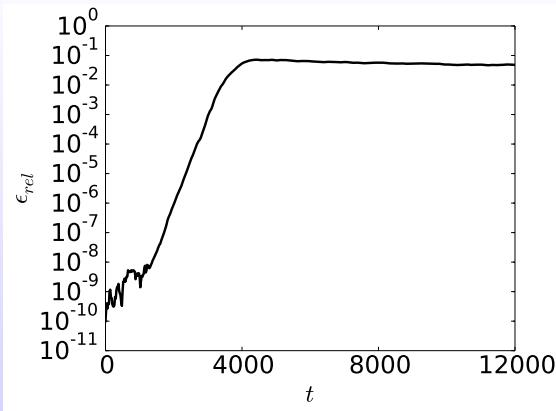


FELTOR (Full-F ELectromagnetic code in TORoidal geometry)



- Both a numerical library and a scientific software package
- 2D and 3D drift- and gyrofluid simulations
- Discontinuous Galerkin methods on structured grids
- Platform independent code from laptop CPUs to hybrid CPU+GPU distributed memory systems

Motivation (2/2)



Accuracy and Reproducibility Issue

- Preconditioned Conjugate Gradient (PCG) to invert elliptic equation
- The issue is with computing residual: $\text{dot}(a,b)$ and $\text{dot}(a,b,c)$
- But also axpby and probably spmv

- 1 Computer Arithmetic
- 2 ExBLAS: Exact BLAS
- 3 Sparse Matrix-Vector Multiplication
- 4 Performance Results
- 5 Discussion and Conclusions

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Problems

- Floating-point arithmetic suffers from **rounding errors**
- Floating-point operations (+, ×) are commutative but **non-associative**

$$(-1 + 1) + 2^{-53} \neq -1 + (1 + 2^{-53}) \quad \text{in double precision}$$

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$2^{-53} \neq 0$ in double precision

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$$(-1 + 1) + 2^{-53} \neq -1 + (1 + 2^{-53}) \quad \text{in double precision}$$

- Consequence: results of floating-point computations **depend on the order of computation**
- Results computed by performance-optimized parallel floating-point libraries may be often **inconsistent**: each run returns a different result

- **Reproducibility** – ability to obtain **bit-wise identical** and **accurate** results from run-to-run on the same input data on the same or different architectures

- Changing Data Layouts:
 - Data partitioning
 - Data alignment
- Changing Hardware Resources
 - Number of threads
 - Fused Multiply-Add support: $a \cdot b + c$
 - Intermediate precision (64 bits, 80 bits, 128 bits, etc)
 - Data path (SSE, AVX, GPU warp, etc)
 - Number of processors
 - Network topology

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- **Fix the Order of Computations**

- Sequential mode: intolerably costly at large-scale systems
- Fixed reduction trees: substantial communication overhead
Example: Intel **C**onditional **N**umerical **R**eproducibility in MKL
($\sim 2x$ for datum, no accuracy guarantees)

Accurate/ Reproducible Summation

Existing Solutions

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- **Eliminate/Reduce the Rounding Errors**

- Fixed-point arithmetic: limited range of values
- Fixed **FP expansions** with **Error-Free Transformations** (EFT)
Example: double-double or quad-double (Briggs, Bailey, Hida, Li)
(work well on a set of relatively close numbers)
- “Infinite” precision: reproducible independently from the inputs
Example: **Kulisch accumulator** (considered **inefficient**)



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- **Libraries**

- **ReproBLAS**: Reproducible BLAS (Demmel, Nguyen, Ahrens)
For BLAS-1, GEMV, and GEMM on CPUs
- **RARE-BLAS**: Repr. Accur. Rounded and Eff. BLAS (Chohra, Langlois, Parello). For BLAS-1 and GEMV on CPUs



Exact Multi-Level Parallel Reduction

Preliminaries

- Fixed FP expansions (FPE) with Error-Free Transformations
- Example: double-double or quad-double (Briggs, Bailey, Hida, Li)
(work well on a set of relatively close numbers)

Algorithm 1 (Dekker and Knuth)

Function[r, s] = twosum(a, b)

1: $r \leftarrow a + b$

2: $z \leftarrow r - a$

3: $s \leftarrow (a - (r - z)) + (b - z)$

Algorithm 2 ($|a| \geq |b|$)

Function[r, s] = twosum(a, b)

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Exact Multi-Level Parallel Reduction

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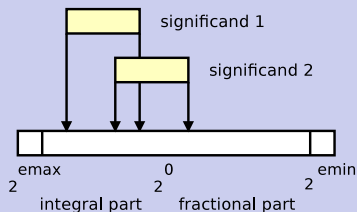
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- “Infinite” precision: reproducible independently from the inputs
- Example: Kulisch accumulator (=16 FLOPs)



Exact Multi-Level Parallel Reduction

Requirements and Limitations

Requirements

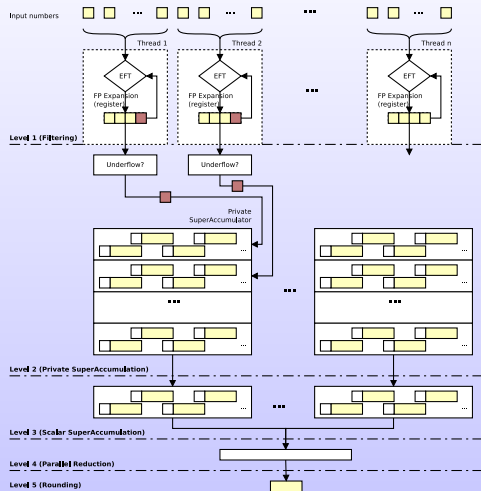
- IEEE 754-2008 full or partial compliance (+, -, *, /, $\sqrt{\quad}$)
- Architecture support and compliance according to IEEE 754-2008 of rounding-to-nearest with breaking ties to even (correct rounding). This is a default widely used rounding mode

Limitations

- Support for underflow numbers
- Exceptions and exception handling

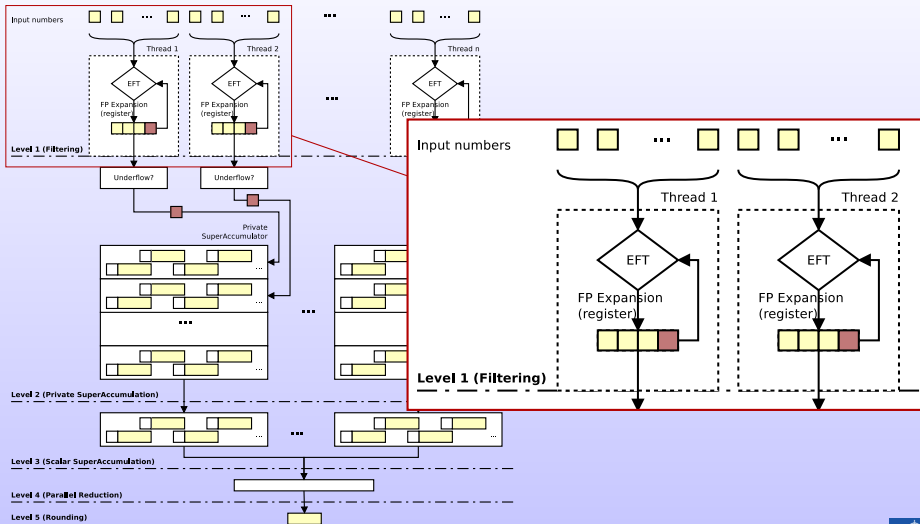


Exact Multi-Level Parallel Reduction

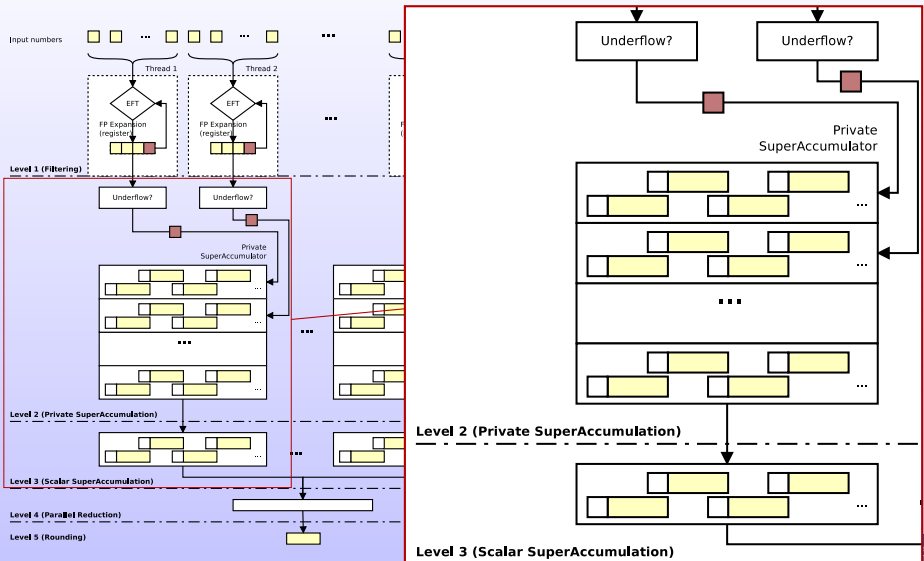


- Parallel algorithm with 5-levels
 - Suitable for today's parallel architectures
 - Based on FPE with EFT and Kulisch accumulator
 - Guarantees “inf” precision
- **bit-wise reproducibility**

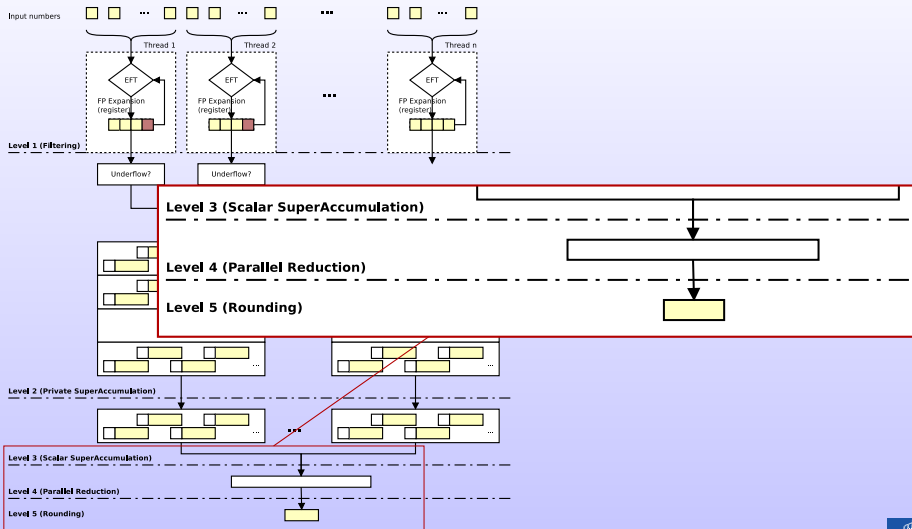
Level 1: Filtering



Level 2 and 3: Scalar Superaccumulator



Level 4 and 5: Reduction and Rounding



ExBLAS Status

- ExBLAS-1: `exsum`^a, `exscal`, `exdot`, `exaxpy`, ...
- ExBLAS-2: `exger`, `exgemv`, `extrsv`, `exsyr`, ...
- ExBLAS-3: `exgemm`, `extrsm`, `exsyr2k`, ...

^aRoutines in `blue` are already in ExBLAS

BLAS-1 routines

- Some are virtually built upon `exsum`
- For instance, `exdot = twoprod + 2exsum`
- `twoprod(a,b)` (= 3 FLOPs):
 - 1: $res \leftarrow a \cdot b$,
 - 2: $err \leftarrow fma(a, b, -res)$

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exaxpy

- $y := \alpha \cdot x + y$
- `fma($\alpha, x[i], y[i]$)` → **correctly rounded** and **reproducible**

exscal

- $x := \alpha \cdot x$ → **correctly rounded** and **reproducible**
- Within LU: $x := 1/\alpha \cdot x$ → **not** correctly rounded
- `exinvscal: $x := x/\alpha$` → **correctly rounded** and **reproducible**

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$$A = \begin{bmatrix} 1 & 7 & 0 & 0 \\ 0 & 2 & 8 & 0 \\ 5 & 0 & 3 & 9 \\ 0 & 6 & 0 & 4 \end{bmatrix}$$

```
ptr = [0 2 4 7 9]
indices = [0 1 1 2 0 2 3 1 3]
data = [1 7 2 8 5 3 9 6 4]
```

The CSR representation of A

Listing 1: SpMV kernel for the CSR sparse matrix format (Bell and Garland 2008)

```
for (int row = 0; row < num_rows; i++) {
    double dot = 0.0;

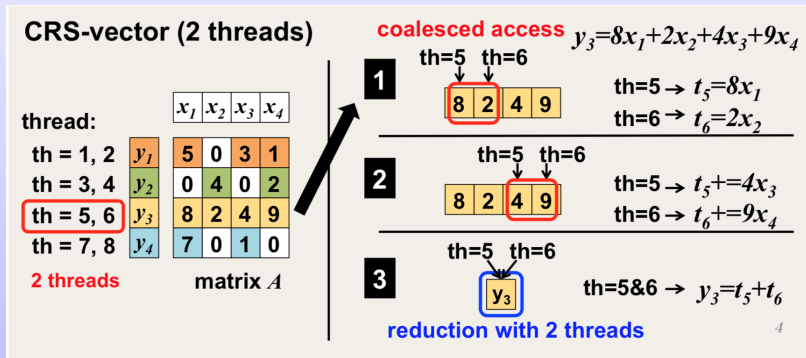
    int row_start = ptr[row];
    int row_end   = ptr[row+1];

    for (int j = row_start; j < row_end; j++)
        dot += data[j] * x[indices[j]];

    y[row] += dot;
}
```

CRS-vector (Bell and Garland 2008)

- Assigns multiple threads (e.g. 32 threads) to compute a single row of the matrix A
- Memory access to the matrix A is coalesced and thus it suits GPUs



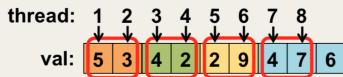
CRS-vector (Reguly and Giles 2012)

- Selecting the suitable number of threads (NT) in proportion to the average number of non-zeros per row
- Reduce NT if the number of non-zeros is less than 32

5	0	3	0
0	4	0	2
0	2	0	9
4	0	7	6

Nonzeros= 9
Rows = 4
Avg nonzeros / row
= $9 / 4 = 2.25$

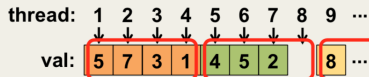
➤ **Optimal NT = 2**



5	7	3	1
0	4	5	2
8	2	0	9
9	3	7	6

Nonzeros= 14
Rows = 4
Avg nonzeros / row
= $14 / 4 = 3.5$

➤ **Optimal NT = 4**



exspmv in brief

- Combine high performing algorithmic versions with `exdot`
- Invoke auto-tuning and optimization strategies

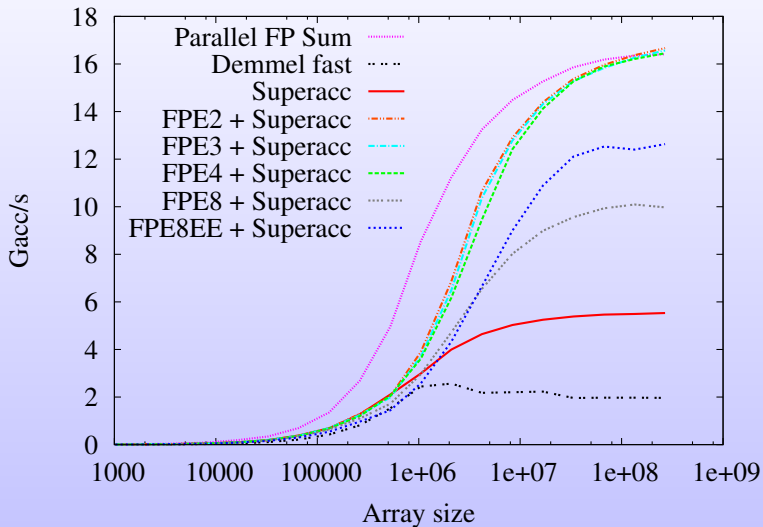
Optimization

- Determining the placement of long accumulators (eg shared memory)
- Using read-only data cache to store the vector x
- Avoiding outermost loop on the number of rows
- Using shuffle instructions for load/ store

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Parallel Reduction

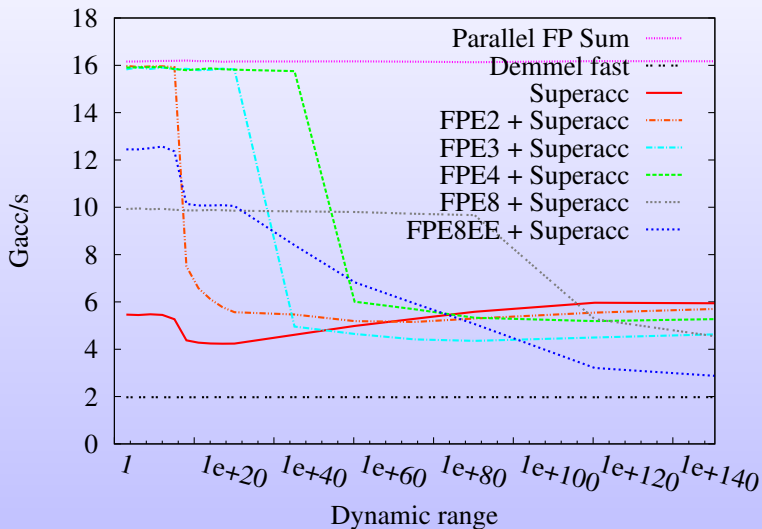
Performance Scaling on NVIDIA Tesla K20c



Parallel Reduction

Data-Dependent Performance on NVIDIA Tesla K20c

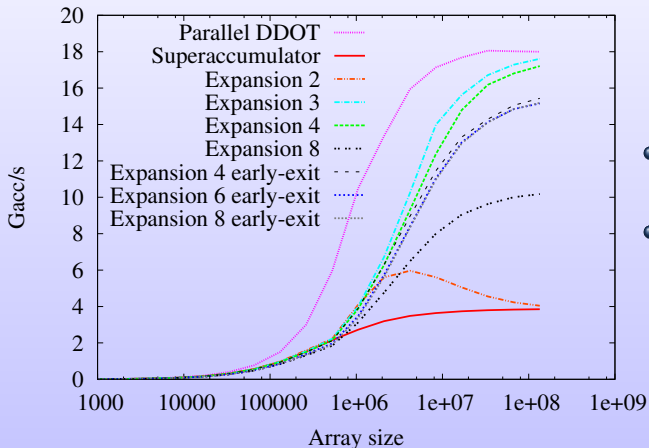
$n = 67e06$



Dot Product

Performance Scaling on NVIDIA Tesla K20c

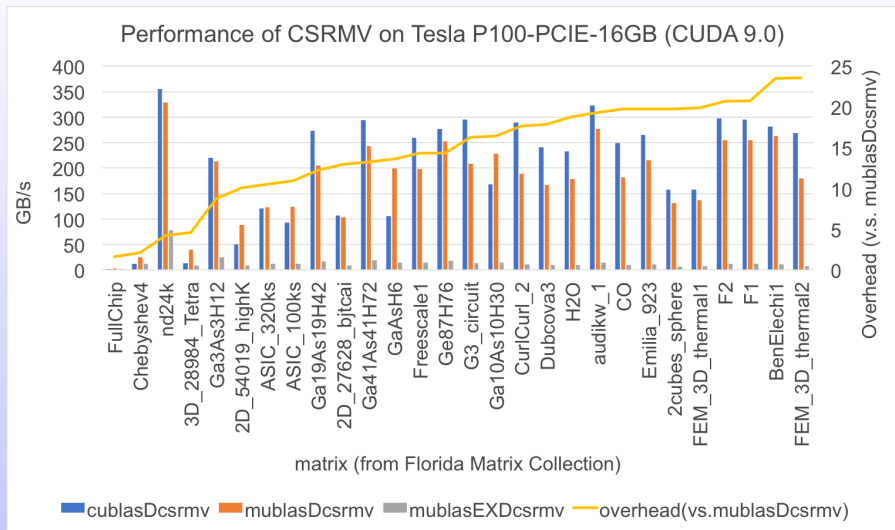
$$\text{DDOT: } \alpha := x^T y = \sum_i^N x_i y_i$$



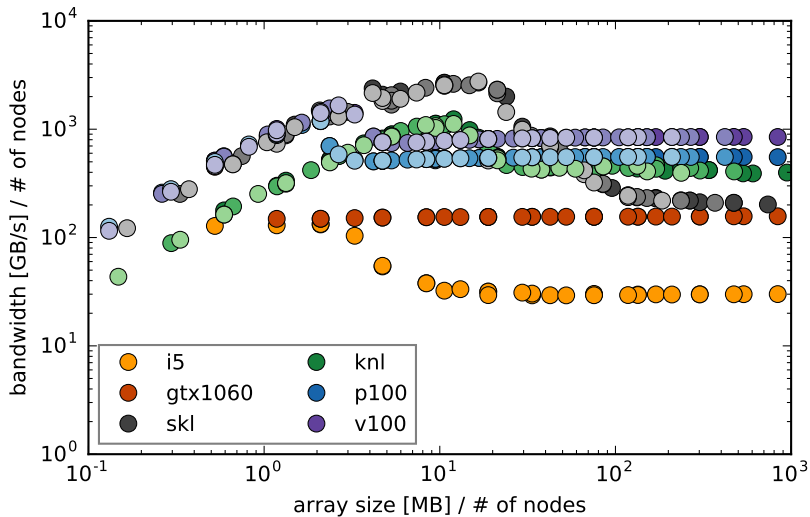
- Based on exsum and twoproduct
- $\text{twoproduct}(a, b)$
 - 1: $r \leftarrow a * b$
 - 2: $s \leftarrow \text{fma}(a, b, -r)$



SpMV: High performing version

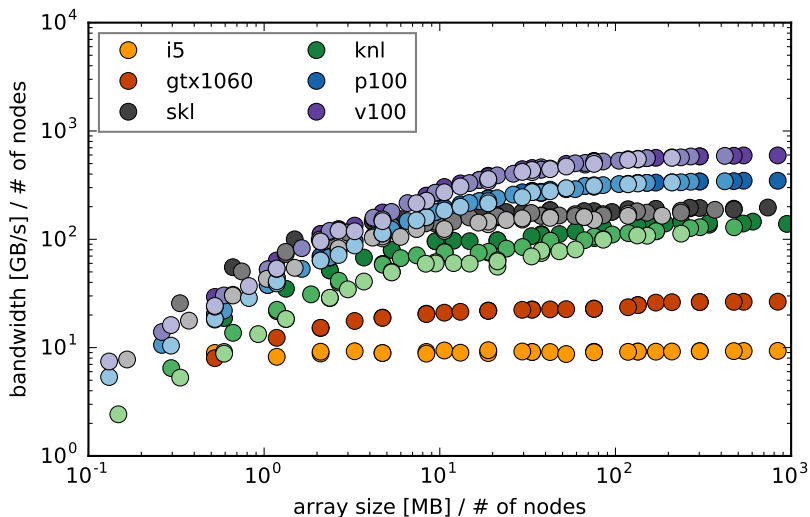


$$\text{axpby: } y := \alpha x + \beta y$$

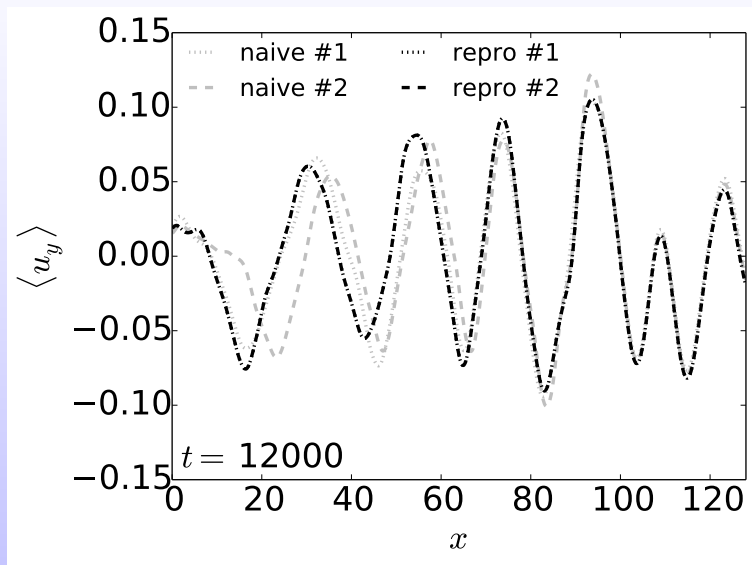


Feltor: dot

$$\text{dot: } \alpha := x^T y = \sum_i^N x_i y_i$$



Feltor: Reproducibility and Accuracy



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S1: Compute the preconditioner $A \rightarrow M \approx LU$	
S2: Initialize $x_0, r_0, z_0, d_0, \beta_0, \tau_0$	
S3: $k := 0$	
S4: while ($\tau_k > \tau_{\max}$)	Iterative PCG solve
S5: $w_k := Ad_k$	(SPMV)
S6: $\rho_k := \beta_k / d_k^T w_k$	(DOT product)
S7: $x_{k+1} := x_k + \rho_k d_k$	(AXPY)
S8: $r_{k+1} := r_k - \rho_k w_k$	(AXPY)
S9: $z_{k+1} := M^{-1} r_{k+1} \approx U^{-1} L^{-1} r_{k+1}$	Apply preconditioner
S10: $\beta_{k+1} := r_{k+1}^T z_{k+1}$	(DOT product)
S11: $\alpha_k := \beta_{k+1} / \beta_k$	
S12: $d_{k+1} := z_{k+1} + \alpha_k d_k$	(AXPY-like)
S13: $\tau_{k+1} := \ r_{k+1} \ _2$	(2-norm)
S14: $k := k + 1$	
S15: endwhile	

Feltor: Reproducible PCG

- Missing components: `spmv` and `nrm2`
- But `spmv` with their specific format

History

1985 was a hardware standard – hoping for hardware adoption

2008 was a meta-standard for programming languages – hardware adopted, hoping for languages

2018 is a bug fix release – catching up with C and searching for other languages

Updates

- Augmented operations $+$, $-$, $*$ (aka `twosum` and `twoproduct`)
 - Considered but dropped from 754-2008
 - Pending hardware implementations encouraged put them back
- **Importance**: extended-precision/ reproducible computations

Conclusions

- Leveraged a long accumulator and EFTs to design **reproducible and correctly-rounded** `exsum` **and** `exdot`
- Delivered reproducible and accurate BLAS-1 routines like `axpy`, `scal`, and `invscal`
- Designed **high performance algorithmic variants** for `cstrmv`
- Ensured reproducibility and accuracy of `cstrmv` through `exdot`
- Provided **bit-to-bit reproducible** results independently from
 - Data permutation, data assignment, partitioning/blocking
 - Thread scheduling
 - Reduction trees

Conclusions and Future Work

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TODO List

- Optimization and auto-tuning of `cstrmv`
- Reproducible Jacobi and Conjugate Gradient methods



Thank you for your attention!

Publications: `pdc.kth.se/~riakymch/pubs`

Code: `https://exblas.lip6.fr`

Soon on GitHub

